

\mathcal{F} smooth manifold

\underline{s} solve EL eqns

$$\nabla_{\underline{u}} \left(\int_M (\nabla_{1,\underline{u}} + \nabla_{2,\underline{u}}) \mathcal{L}(x,y) dy - \nabla_{\underline{u}} \circ \right) = 0 \quad \forall \underline{u} \in \mathcal{J}^{\text{tot}}$$

1) unitary invariance for causal fermion systems

$$\dim \mathcal{X} < \infty$$

$$\mathcal{F} = \mathcal{F}_{\zeta}^{\text{reg}}$$

let $A \in L(\mathcal{X})$ symmetric

$$U_t = e^{itA}$$

family of unitary transformations

let $x \in \mathcal{F}$

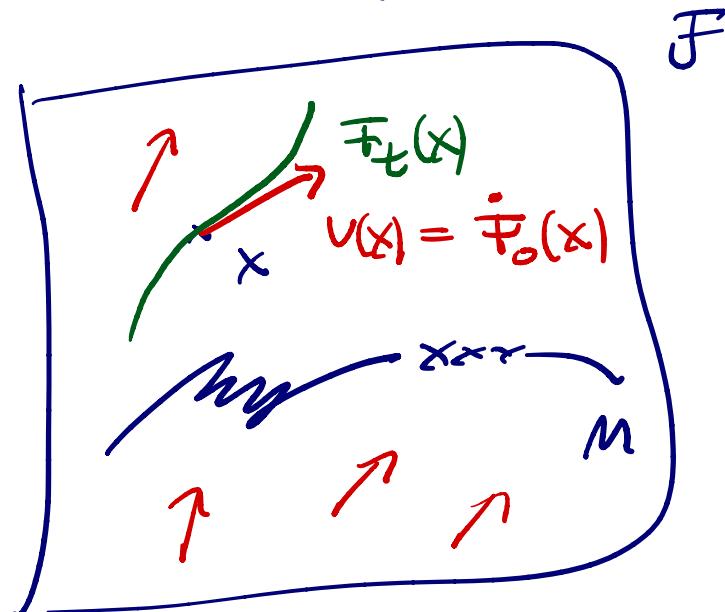
$$F_t(x) := U_t x U_t^{-1}$$

$$v(x) := \frac{d}{dt} F_t(x) \Big|_{t=0}$$

$$= i [A, x]$$

commutator vector field

$$C_A(x) = i [A, x]$$



$v(x) := C_A(x)$ with $x \in M$ is in $\Gamma(M, T\mathcal{F})$

$\underline{v} := (0, v)$ is the commutator jet

The Lagrangian is unitarily invariant

$$\mathcal{L}(F_t(x), F_t(y)) = \mathcal{L}(x, y)$$

Lemma: For any symmetric $A \in L(\mathcal{X})$, the corresponding commutator jet satisfies the linearized field eqns.

$$\begin{aligned}
 \text{Proof: } & \frac{d}{dt} \mathcal{L}(F_t(x), F_t(y)) \Big|_{t=0} \\
 &= (\nabla_{1,\underline{v}} + \nabla_{2,\underline{v}}) \mathcal{L}(x,y) = 0 \\
 &\nabla_{\underline{v}} \circ = 0 \quad (\text{because } \underline{v} \text{ has no scalar component}) \\
 \Rightarrow & \left(\int_M (\nabla_{1,\underline{v}} + \nabla_{2,\underline{v}}) \mathcal{L}(x,y) dg(y) - \nabla_{\underline{v}} \circ \right) = 0
 \end{aligned}$$

$$\forall x \in \mathcal{F}$$

$$\Rightarrow \nabla_{\underline{v}} \left(\int_M (\nabla_{1,\underline{v}} + \nabla_{2,\underline{v}}) \mathcal{L}(x,y) dg(y) - \nabla_{\underline{v}} \circ \right) = 0$$

Note: The term when $\nabla_{\underline{v}}$ acts on \underline{v} vanishes
 because of the EL equations. □

2) Diffeomorphism invariance of M

Let $\underline{\Phi}_t : M \rightarrow M$ family of diffeomorphisms

$$v(x) := \frac{d}{dt} \underline{\Phi}_t(x) \Big|_{t=0}$$

infinitesimal generator

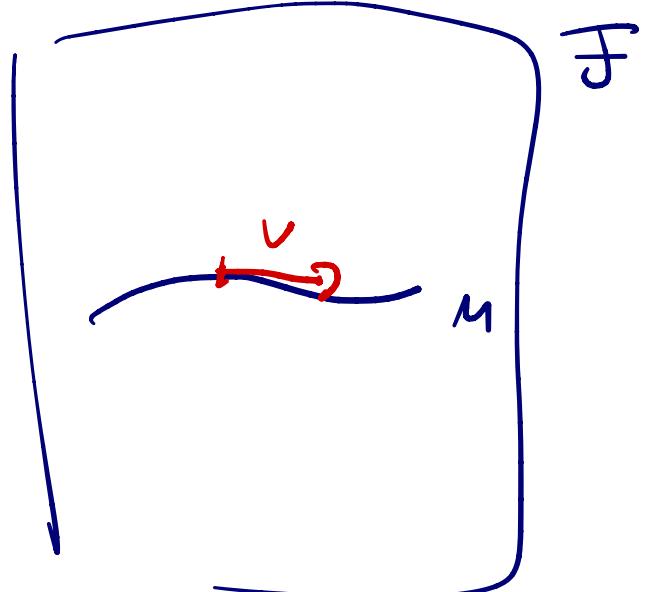
vector field on M

$$(\underline{\Phi}_t)_* S =: \tilde{S}_t$$

the change of the measure is described infinitesimally by the divergence of v .

Def: Spacetime $M := \cup_{t \geq 0} S_t$ has a smooth manifold structure if

- (i) M is a k -dim. smooth submanifold of \mathcal{F}



(iii) In a chart (x^i, U) of M , the measure g can be written as

$$dg = h(x) d^k x$$

with h a smooth positive function.

Let $v \in \Gamma(M, TM)$ be a vector field on M

$$(v \in \Gamma(M, JF) \text{ and } v(x) \in T_x M \subset T_x F)$$

The divergence of v is defined by

$$\operatorname{div} v = \frac{1}{h} \partial_i (h v^i)$$

is independent of the choice of charts. This can be seen in analogy to the kernel formula

$$\operatorname{div} v = \frac{1}{\sqrt{\det g}} \partial_i (\sqrt{\det g} v^i)$$

in Riemannian geometry where $dx_m = \sqrt{\det g} d^k x$.

The jet $\underline{v} = (\operatorname{div} v, v)$ is an overline{overline{solution}}

Lemma: $\underline{v} = (\operatorname{div} v, v)$ is a solution of the linearized field eqns if $v \in \Gamma_0(M, Tu)$ and L is smooth has compact support

Proof: Let $f \in C^\infty(M, \mathbb{R})$. $\stackrel{=}{=} v^i \partial_i f$

$$\int_M D_v f \, dg = \int_M D_v f \, h(x) d^k x$$

$$= - \int_M f(x) \underbrace{\frac{1}{h} \partial_i (h v^i)}_{\operatorname{div} v} \underbrace{h d^k x}_{dg} = - \int f \operatorname{div} v \, dg$$

$$\Rightarrow \int_M D_{\underline{v}} f \, dg = 0$$

$$\begin{aligned} \langle \underline{u}, D_{\underline{v}} \rangle &= D_{\underline{u}} \left(\int_M (D_{\underline{u}, \underline{v}} + \cancel{D_{\underline{v}, \underline{u}}}) L(x, y) \, dg(y) - D_{\underline{v}} \sigma \right) \\ &= D_{\underline{u}} D_{\underline{v}} L(x) \\ &= D_{\underline{v}} D_{\underline{u}} L(x) \quad \leftarrow \text{both derivatives act on } L \\ &= D_{\underline{v}} (D_{\underline{u}(x)} L(x)) - D_{D_{\underline{v}}, \underline{u}} L(x) \\ &\quad \uparrow \text{acts on both } L \text{ and } \underline{u}(x) \end{aligned}$$

$$D_{\underline{u}} L(x) = 0 \quad \forall x \in M \text{ due to EL eqns}$$

Since \underline{v} is tangential to M ,

$D_{\underline{v}} (D_{\underline{u}} L)$ exists on M and vanishes

$$D_{D_{\underline{v}}, \underline{u}} L = 0 \quad \text{due to EL eqn.}$$

□

generalizations:

- v has no compact support, but decays suitably at infinity.
- L not smooth: careful with y^{test}, \dots

